FLEXIBILITY TO REACH AND IMAGE RENAL TUMORS



New Rob12C4* ultrasound transducer to enhance robotic-assisted partial nephrectomy procedures.



See More Anatomy

Confidently visualize critical anatomy with excellent image quality, wide field of view, and sensitive color Doppler.



Physician control

Maintain control with a stable grasp using the proprietary fin designed for ProGrasp™ Forceps.

Seamless integration of images with the TilePro™ multi-input display**.

Integrate conveniently into crowded OR using 3.5 m cable and small system footprint.

Easy cleaning and sterilization options.

Precision

Measure tumor size in real-time.

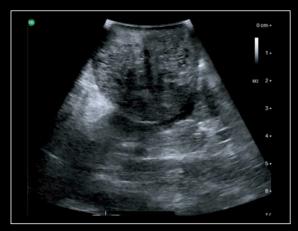
Correlate tumor border location between ultrasound and endoscope images for precise removal of tumors.

REACH MORE. SEE MORE. TREAT MORE.

Real-time intraoperative ultrasound helps¹:

- Confirm tumor borders and depth to minimize:
 - warm ischemia time
 - positive margins
 - injury to arteries
 - resection of healthy tissue

- Visualize endophytic tumors
- Adapt pre-operative surgical plans
- Assess arterial location, vascularity, and perfusion



Renal tumor Rob12C4 transducer



Renal parenchyma and exophytic renal tumor with color Doppler Rob12C4 transducer



Seamless integration of images with TilePro™ multi-input display**

'The Robotic Transducer Rob12C4 has not been licensed by Health Canada; Rob12C4 is compatible with bk5000 software version 5.16.2 and higher.
"Trademark of Intuitive Surgical, Inc.

Di Cosmo et al. (2018). Intraoperative ultrasound in robot-assisted partial nephrectomy: State of the art. Archivio Italiano di Urologia e Andrologia. 90. 195. 10.4081/aiua.2018.3.195

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